



# Understanding Gradient Clipping in Private SGD: A Geometric Perspective



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## Contribution

- A symmetricity-based distribution-aware analysis on clipping bias
- Theoretical and empirical studies of the effect of gradient clipping in DP-SGD
- A pre-clipping perturbation mechanism to reduce clipping bias in DP-SGD

## Motivation

- Private SGD with gradient clipping [1] works well in practice and the clipping threshold is an important parameter to tune
- Intuitively, gradient clipping may make Private SGD fail to converge
- The effect of gradient clipping is not well-understood

## Differentially-private SGD (DP-SGD) and gradient clipping

Update rule:

$$x_{t+1} = x_t - \alpha \left( \left( \frac{1}{|S_t|} \sum_{i \in S_t} \text{clip}(\nabla f(x_t) + \xi_{t,i}, c) \right) + Z_t \right)$$

$Z_t \sim \mathcal{N}(0, \sigma^2 I)$ , the noise to achieve privacy  
 A subset of training samples      Per-sample gradient

Gradient clipping:

$$\text{clip}(g, c) = g \cdot \max \left( 1, \frac{c}{\|g\|} \right)$$

## SGD with gradient clipping

To better understand convergence, first consider **SGD with gradient clipping** (batch size=1):

$$x_{t+1} = x_t - \alpha \text{clip}(\nabla f(x_t) + \xi_t, c) := x_t - \alpha g_t$$

clipped gradient

## Convergence of SGD with gradient clipping

An intermediate convergence result:

**Theorem.** Let  $G$  be the Lipschitz constant of  $\nabla f$  such that  $\|\nabla f(x) - \nabla f(y)\| \leq G\|x - y\|, \forall x, y$ . For SGD with gradient clipping of threshold  $c$ , if we set  $\alpha = \frac{1}{\sqrt{T}}$ , we have

$$\frac{1}{T} \sum_{t=1}^T \mathbb{E}[\langle \nabla f(x_t), g_t \rangle] \leq \frac{D_f}{\sqrt{T}} + \frac{G}{2\sqrt{T}} c^2$$

where  $D_f = f(x_1) - \min_x f(x)$ .

However, what can it say about convergence?

1. **Convergence:** We have  $\mathbb{E}[\langle \nabla f(x_t), g_t \rangle] = \|\nabla f(x_t)\|^2$  when clipping is always inactive ( $c$  is very large).
2. **Divergence:** The above may not hold when clipping can be active ( $c$  is relatively small).

## Symmetricity helps convergence in SGD with gradient clipping

When distribution of stochastic gradient is symmetric:

**Theorem.** Assume  $\tilde{p}(\xi_t) = \tilde{p}(-\xi_t)$ , gradient clipping with threshold  $c$  has the following properties.

1. If  $\|\nabla f(x_t)\| \leq \frac{3}{4}c$ , then  $\mathbb{E}_{\xi_t \sim \tilde{p}}[\langle \nabla f(x_t), g_t \rangle] \geq \|\nabla f(x_t)\|^2 \mathbb{P}_{\xi_t \sim \tilde{p}}(\|\xi_t\| < \frac{c}{4})$
  2. If  $\|\nabla f(x_t)\| > \frac{3}{4}c$ , then  $\mathbb{E}_{\xi_t \sim \tilde{p}}[\langle \nabla f(x_t), g_t \rangle] \geq \frac{3}{4}c \|\nabla f(x_t)\| \mathbb{P}_{\xi_t \sim \tilde{p}}(\|\xi_t\| < \frac{c}{4})$
- Implies convergence

## Convergence of SGD and DP-SGD with gradient clipping

SGD with gradient clipping:

**Theorem.** For SGD with gradient clipping, set  $\alpha = \frac{1}{\sqrt{T}}$ . Suppose true gradient noise distribution is  $p$ , choose  $\tilde{p}_t(\xi) = \tilde{p}_t(-\xi)$ , then the following holds:

$$\frac{1}{T} \sum_{t=1}^T \mathbb{P}_{\xi_t \sim \tilde{p}_t}(\|\xi_t\| < \frac{c}{4}) \min \left\{ \|\nabla f(x_t)\|, \frac{3}{4}c \right\} \|\nabla f(x_t)\| \leq \frac{D_f}{\sqrt{T}} + \frac{G}{2\sqrt{T}} c^2 - \frac{1}{T} \sum_{t=1}^T b_t$$

where  $b_t := \int \langle \nabla f(x_t), \text{clip}(\nabla f(x_t) + \xi_t, c) \rangle (p_t(\xi_t) - \tilde{p}_t(\xi_t)) d\xi_t$ .

DP-SGD with gradient clipping:

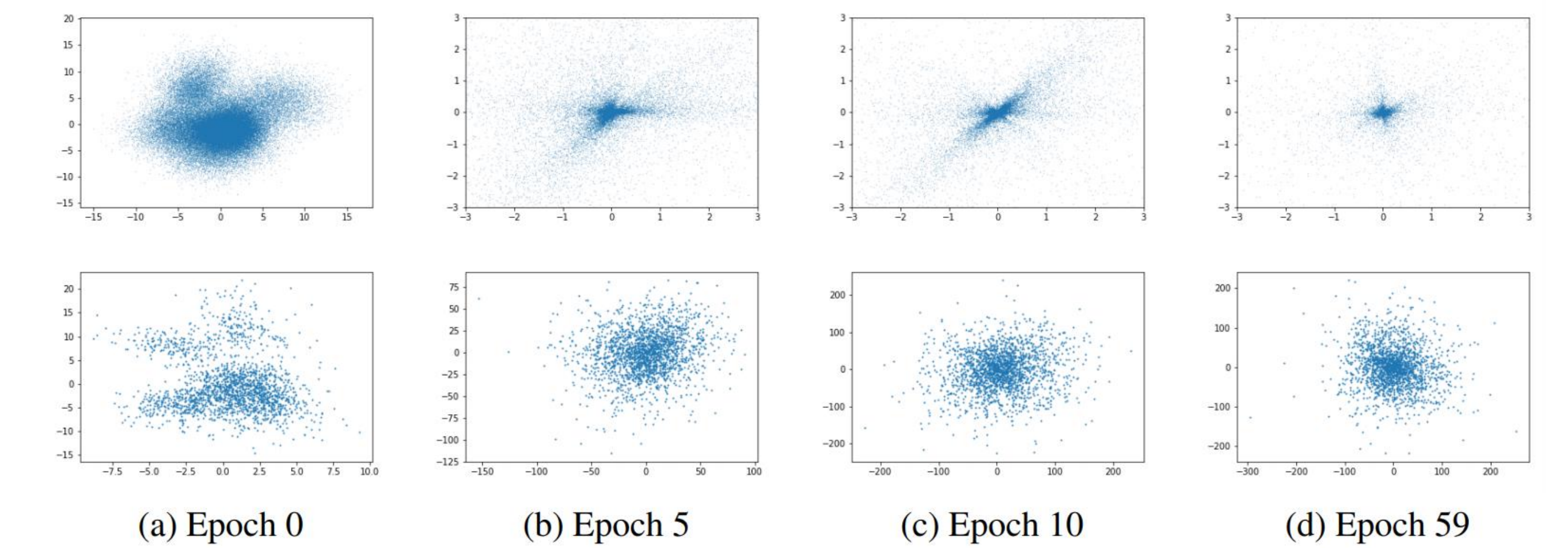
**Theorem.** Let  $d$  be the dimensionality of the parameters. For DP-SGD with gradient clipping and privacy parameters  $(\epsilon, \delta)$ , choose  $\tilde{p}_t(\xi_t) = \tilde{p}_t(-\xi_t)$ , there exist  $u$  and  $v$  such that

$$\frac{1}{T} \sum_{t=1}^T \mathbb{P}_{\xi_t \sim \tilde{p}}(\|\xi_t\| < \frac{c}{4}) h_c(\|\nabla f(x_t)\|) \leq \left( \frac{1}{2}v + \frac{3}{2} \right) c \frac{\sqrt{D_f G d \ln(\frac{1}{\delta})}}{n\epsilon} + \frac{1}{T} \sum_{t=1}^T W_{\nabla f(x_t), c}(\tilde{p}_t, p_t)$$

where  $h_c(y) = \min(y^2, \frac{3}{4}cy)$  and  $W_{v,c}(p, p')$  is the Wasserstein distance between  $p$  and  $p'$  with metric function  $d_{v,c}(a, b) = |\langle v, \text{clip}(v+a, c) \rangle - \langle v, \text{clip}(v+b, c) \rangle|$  and  $D_f \geq f(x_1) - \min_x f(x)$ .

## Gradient symmetricity

Per-sample gradient of a convnet projected into 2d space using a random matrix (top row for MNIST, bottom row for CIFAR-10):



## Mitigate clipping bias by pre-clipping noise

DP-SGD with pre-clipping noise:

$$x_{t+1} = x_t - \alpha \left( \left( \frac{1}{|S_t|} \sum_{i \in S_t} \text{clip}(\nabla f(x_t) + \xi_{t,i} + k\zeta_{t,i}, c) \right) + Z_t \right)$$

$\zeta_{t,i} \sim \mathcal{N}(0, I)$

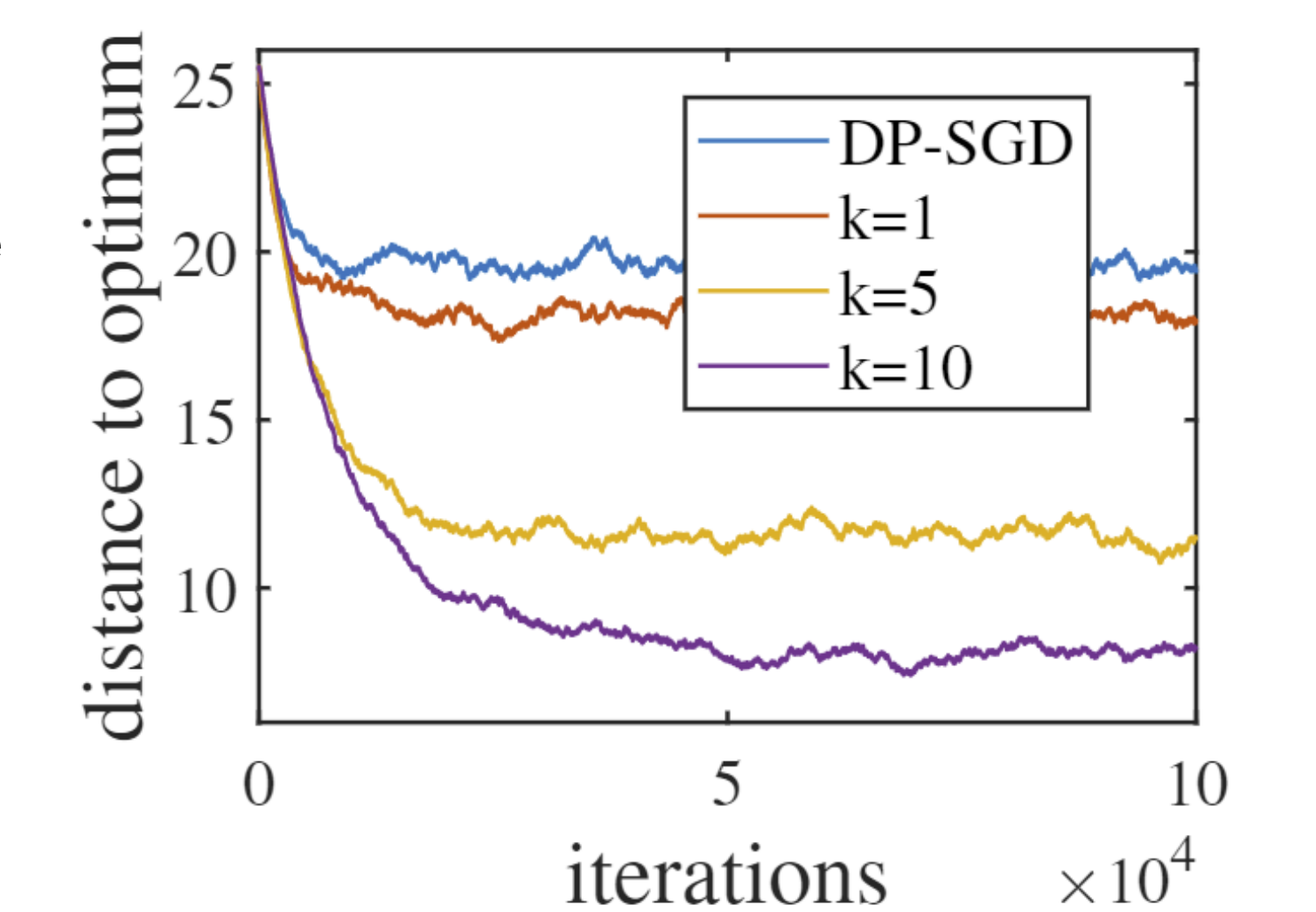
**Theorem.** Let  $g_t = \text{clip}(\nabla f(x_t) + \xi_t + k\zeta_t, c)$  and  $\zeta_t \sim \mathcal{N}(0, I)$ . Then gradient clipping algorithm has following properties:

$$\mathbb{E}_{\xi_t \sim p, \zeta_t}[\langle \nabla f(x_t), g_t \rangle] \geq \|\nabla f(x_t)\| \min \left\{ \|\nabla f(x_t)\|, \frac{3}{4}c \right\} \mathbb{P}(\|k\zeta_t\| < \frac{c}{4}) - O\left(\frac{\sigma_{\xi_t}^2}{k^2}\right)$$

where  $\sigma_{\xi_t}^2$  is the variance of the gradient noise  $\xi_t$ .

## Benefit of pre-clipping noise

Run DP-SGD with pre-clipping noise on a 10d synthetic dataset with asymmetric gradient distribution



## References

[1]. Abadi, Martin, et al. "Deep learning with differential privacy." 2016 ACM SIGSAC Conference on Computer and Communications Security. 2016.